Strategic Interactive Decision-Making

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ACTION
A BOUNTY FOR
DEAD COBRAS!





ACTION
A BOUNTY FOR
DEAD COBRAS!



EFFECT

PEOPLE START COBRA FARMING





ACTION A BOUNTY FOR DEAD COBRAS!



EFFECT

PEOPLE START
COBRA FARMING

Anything that can go wrong will go wrong.

Murphy's Law





ACTION A BOUNTY FOR DEAD COBRAS!



EFFECT

PEOPLE START
COBRA FARMING

Any system that can be gamed will be gamed.































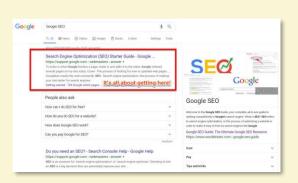










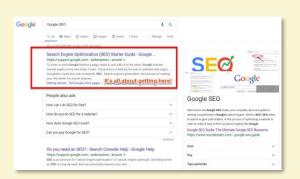


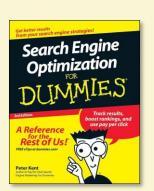




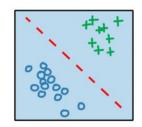


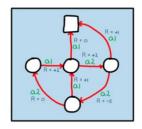




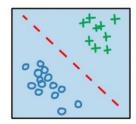


Supervised Learning

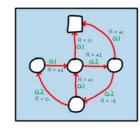




Supervised Learning

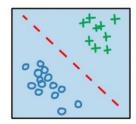


Adversarial Robustness

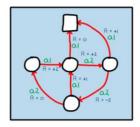


Adversarial Robustness

Supervised Learning



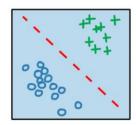
Adversarial Robustness



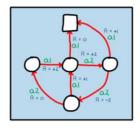
Adversarial Robustness



Supervised Learning



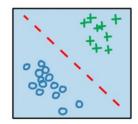
Adversarial Robustness Strategic Classification



Adversarial Robustness
Corruption-Robust RL



Supervised Learning

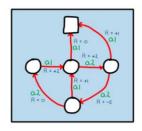


Adversarial Robustness

<u>Strategic Classification</u>



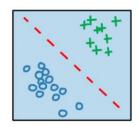
Reinforcement Learning



Adversarial Robustness
Corruption-Robust RL



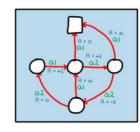
Supervised Learning



Adversarial Robustness
<u>Strategic Classification</u>

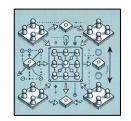


Reinforcement Learning



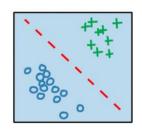
Adversarial Robustness
Corruption-Robust RL

Mechanism Design





Supervised Learning



Adversarial Robustness

<u>Strategic Classification</u>

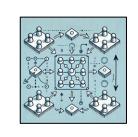


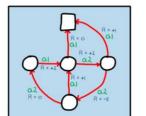
Strategic Interactive

Decision-Making

Adversarial Robustness
Corruption-Robust RL

Mechanism Design







Strategic Linear Contextual Bandits

joint work with Aadirupa Saha, Christos Dimitrakakis, Haifeng Xu

recommends the channels' content

maximizing individual exposure / profit



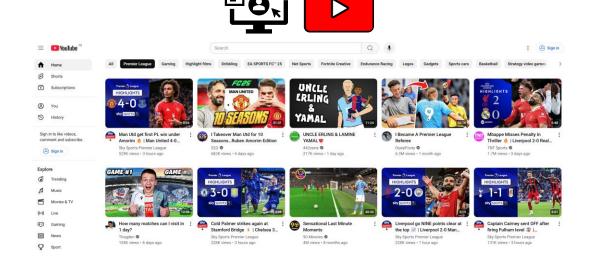
maximizing platform performance

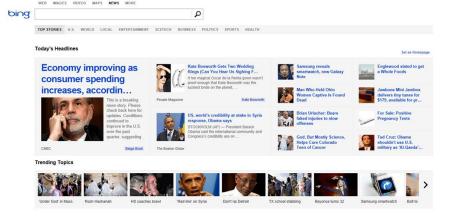
- (1) make good recommendations
- (2) incentivize good content / truthfulness



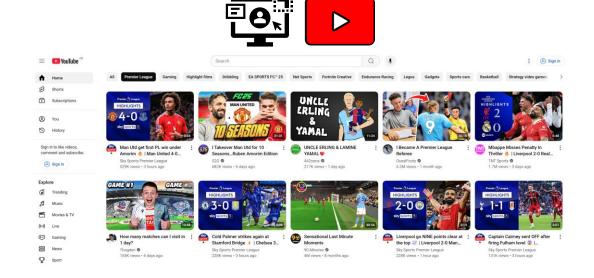


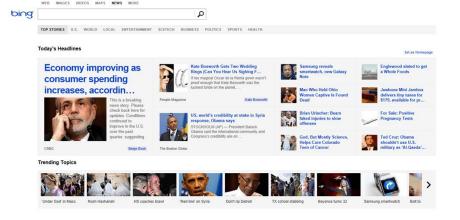




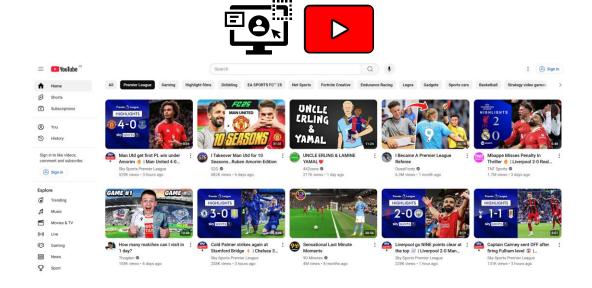


• T rounds, K arms (

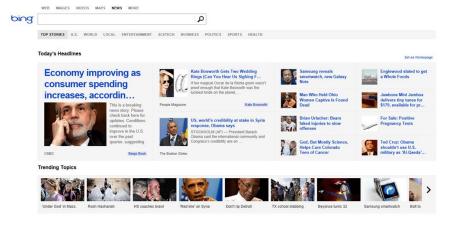




For t = 1, ..., T:



• T rounds, K arms (



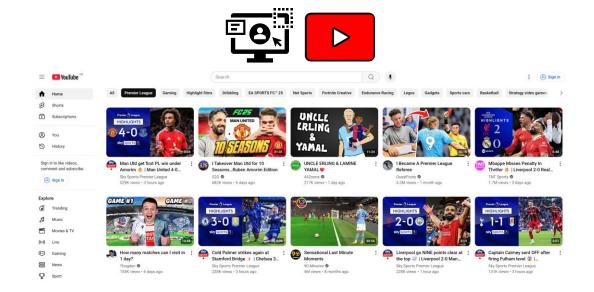
• T rounds, K arms (

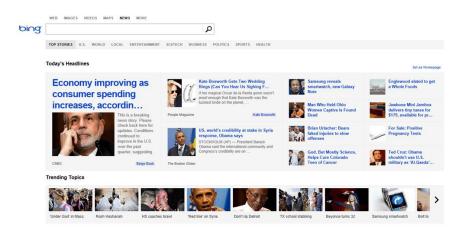
For t = 1, ..., T:

1) Algorithm observes arm-specific contexts $x_{t,1}^* = \dots, x_{t,K}^* = \dots$

,...,
$$x_{t.K}^* =$$

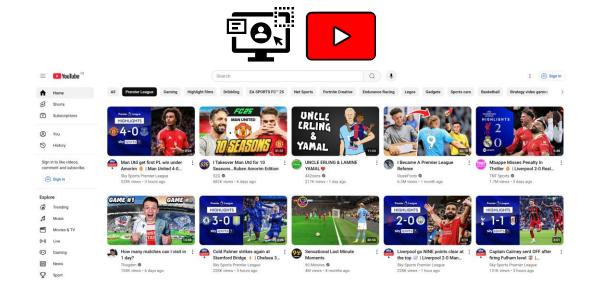
$$\in \mathbb{R}^d$$

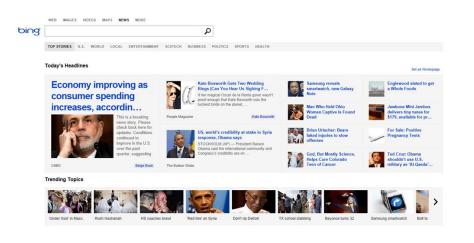




• T rounds, K arms (

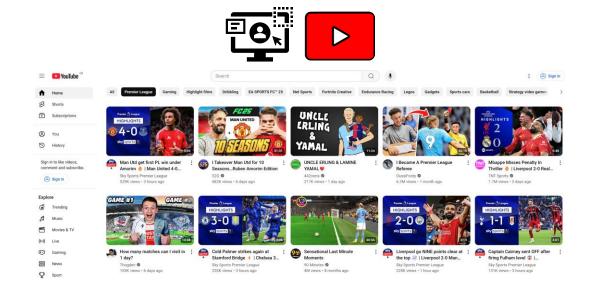
- 1) Algorithm observes arm-specific contexts $x_{t,1}^* = \dots, x_{t,K}^* = \in \mathbb{R}^d$
- 2) Algorithm plays arm $i_t = \in [K]$ and receives reward $r_t^*(i_t) \coloneqq$

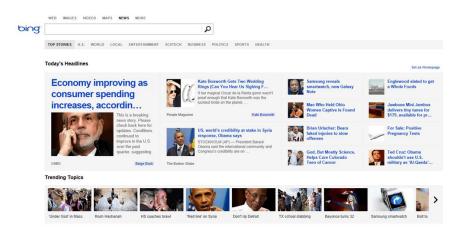




• T rounds, K arms (

- 2) Algorithm plays arm $i_t = \in [K]$ and receives reward $r_t^*(i_t) \coloneqq$

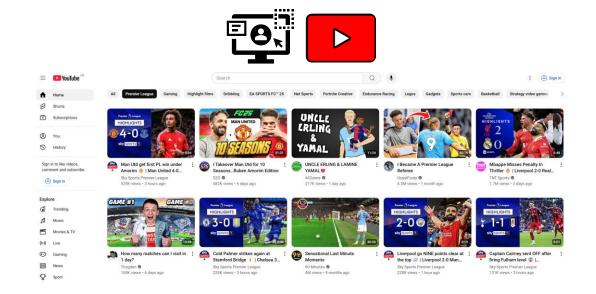


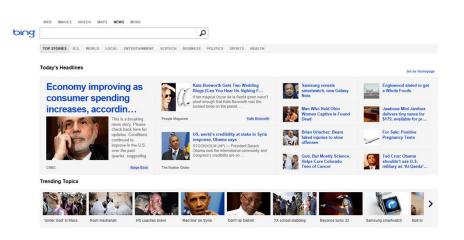


• T rounds, K arms (

- 1) Algorithm observes arm-specific contexts $x_{t,1}^* = \{x_t\}$, ..., $x_{t,K}^* = \{x_t\}$
- 2) Algorithm plays arm $i_t = \bigcup_{t \in K} \in [K]$ and receives reward $r_t^*(i_t) \coloneqq$

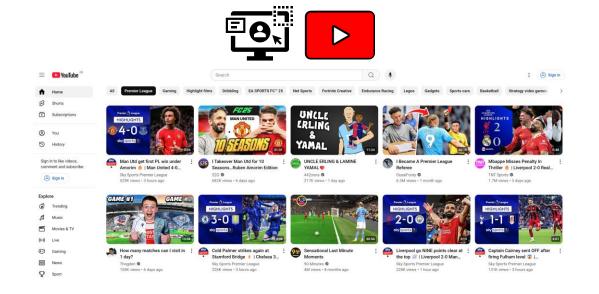


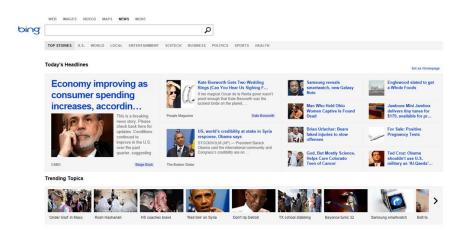




• T rounds, K arms (

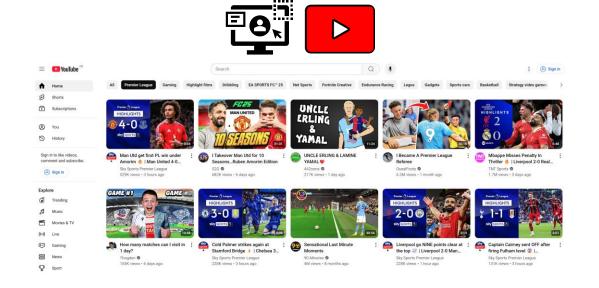
- 2) Algorithm plays arm $i_t = \mathbb{E} \in [K]$ and receives reward $r_t^*(i_t) \coloneqq \langle \theta^*, x_{t,i_t}^* \rangle + \eta_t$

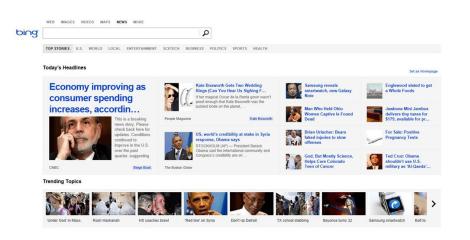




• T rounds, K arms (

- 2) Algorithm plays arm $i_t = \{k\}$ and receives reward $r_t^*(i_t) \coloneqq \langle \theta^*, x_{t,i_t}^* \rangle + \eta_t \}$





• T rounds, K arms (

- 2) Algorithm plays arm $i_t = \mathbb{E} \in [K]$ and receives reward $r_t^*(i_t) \coloneqq \langle \theta^*, x_{t,i_t}^* \rangle + \eta_t$

• T rounds, K arms (

For t = 1, ..., T:

- 2) Algorithm plays arm $i_t = \begin{bmatrix} E \\ E \end{bmatrix} \in [K]$ and receives reward $r_t^*(i_t) \coloneqq \langle \theta^*, x_{t,i_t}^* \rangle + \eta_t$

Algorithm maximizes cumulative reward

$$\sum_{t=1}^{T} r_t(i_t)$$

Linear Contextual Bandits

• T rounds, K arms (

For t = 1, ..., T:

- 1) Algorithm observes arm-specific contexts $x_{t,1}^* = \{x_t, x_{t,k}^* = x_t\} \in \mathbb{R}^d$ 2) Algorithm plays arm $i_t = \{x_t, x_{t,i_t}^* = x_t\} \in \mathbb{R}^d$ unknown

$$R_T = \mathbb{E}\left[\sum_{t=1}^T \max_{i \in [K]} \langle \theta^*, x_{t,i}^* \rangle - \langle \theta^*, x_{t,i_t}^* \rangle\right]$$

Linear Contextual Bandits

• T rounds, K arms (

For t = 1, ..., T:



- 1) Algorithm observes arm-specific contexts $x_{t,1}^* = \{x_t, x_{t,K}^* = \{x_t, x_$ unknown

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arm = strategic agent

For t = 1, ..., T:

- 1) Every arm $i \in [K]$ privately observes its context $x_{t,i}^* = \mathbb{R}^d$
- 2) Every arm $i \in [K]$ reports a gamed context $x_{t,i} = \in \mathbb{R}^d$ to the Algorithm
- 3) Algorithm plays arm $i_t = \{K\}$ and receives reward $r_t^*(i_t) \coloneqq \langle \theta^*, x_{t,i_t}^* \rangle + \eta_t$

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Algorithm minimizes expected regret

$$R_T = \mathbb{E}\left[\sum_{t=1}^T \max_{i \in [K]} \langle \theta^*, x_{t,i}^* \rangle - \langle \theta^*, x_{t,i_t}^* \rangle\right]$$

$$\mathbb{E}\left[\sum_{t=1}^{T} 1(i_t = i)\right]$$

Arms respond in Equilibrium: arm strategies ∈ NE(Algorithm)

For t = 1, ..., T:

- 1) Every arm $i \in [K]$ privately observes its context $x_{t,i}^* = \mathbb{R}^d$
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Arms respond in **Equilibrium**: arm strategies ∈ NE(Algorithm)

For
$$t = 1, ..., T$$
: \checkmark repeated interaction \bigcirc

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For
$$t = 1, ..., T$$
: \checkmark repeated interaction \bigcirc

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- unbounded manipulation 2) Every arm $i \in [K]$ reports a **gamed** context $x_{t,i} = \mathbb{R}^d$ to the **Algorithm**
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Algorithm minimizes expected regret

$$R_T = \mathbb{E}\left[\sum_{t=1}^T \max_{i \in [K]} \langle \theta^*, x_{t,i}^* \rangle - \langle \theta^*, x_{t,i_t}^* \rangle\right]$$

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Arms respond in **Equilibrium**: **arm strategies** ∈ NE(Algorithm)

For
$$t = 1, ..., T$$
: \checkmark repeated interaction \bigcirc

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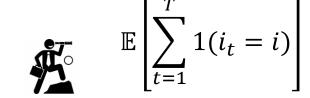
multiple competing agents



Algorithm minimizes expected regret

$$R_T = \mathbb{E}\left[\sum_{t=1}^T \max_{i \in [K]} \langle \theta^*, x_{t,i}^* \rangle - \langle \theta^*, x_{t,i_t}^* \rangle\right]$$

Every Arm *i* maximizes its **#selections**



Arms respond in **Equilibrium**: arm strategies ∈ NE(Algorithm)

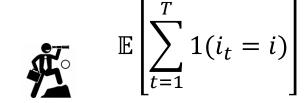
For t = 1, ..., T: \checkmark repeated interaction \bigcirc

- 1) Every arm $i \in [K]$ privately observes its context $x_{t,i}^* = \mathbb{R}^d$
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- 3) Algorithm plays arm $i_t = \bigcup_{t \in [K]} \in [K]$ and receives reward $r_t^*(i_t) \coloneqq \langle \theta^*, x_{t,i_t}^* \rangle + \eta_t$ multiple competing agents unknown environment

Algorithm minimizes expected regret

$$R_T = \mathbb{E}\left[\sum_{t=1}^T \max_{i \in [K]} \langle \theta^*, x_{t,i}^* \rangle - \langle \theta^*, x_{t,i_t}^* \rangle\right]$$

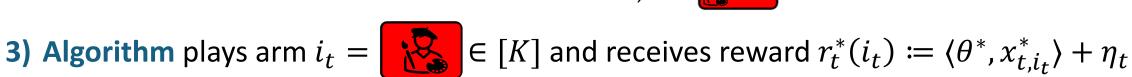
Every Arm *i* maximizes its **#selections**



Arms respond in **Equilibrium**: **arm strategies** ∈ NE(Algorithm)

For t = 1, ..., T: repeated interaction

- 1) Every arm $i \in [K]$ privately observes its context $x_{t,i}^* = \mathbb{R}^d$
- unbounded manipulation 2) Every arm $i \in [K]$ reports a gamed context $x_{t,i} = \mathbb{R}^d$ to the Algorithm



multiple competing agents



unknown environment internal state word environment



Algorithm minimizes expected regret

$$R_T = \mathbb{E}\left[\sum_{t=1}^T \max_{i \in [K]} \langle \theta^*, x_{t,i}^* \rangle - \langle \theta^*, x_{t,i_t}^* \rangle\right]$$

Every Arm i maximizes its #selections



$$\mathbb{E}\left|\sum_{t=1}^{I}1(i_{t}=i)\right|$$



Arms respond in **Equilibrium**: **arm strategies** ∈ NE(Algorithm)

For t = 1, ..., T: repeated interaction

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multiple competing agents



known environment environment



Algorithm minimizes expected regret

$$R_T = \mathbb{E}\left[\sum_{t=1}^T \max_{i \in [K]} \langle \theta^*, x_{t,i}^* \rangle - \langle \theta^*, x_{t,i_t}^* \rangle\right]$$

Every Arm i maximizes its #selections



$$\mathbb{E}\left|\sum_{t=1}^{T}1(i_{t}=i)\right|$$



Arms respond in **Equilibrium**: arm strategies ∈ NE(Algorithm)

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- 1) Every arm $i \in [K]$ privately observes its context $x_{t,i}^* = \mathbb{R}^d$
- 2) Every arm $i \in [K]$ reports a **gamed** context $x_{t,i} = \mathbb{R}^d$ to the **Algorithm**
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known environment environment





Arms respond in **Equilibrium**: **arm strategies** ∈ NE(Algorithm)

For t = 1, ..., T:

- 1) Every arm $i \in [K]$ privately observes its context $x_{t,i}^* = \mathbb{R}^d$
- 2) Every arm $i \in [K]$ reports a **gamed** context $x_{t,i} = \mathbb{R}^d$ to the **Algorithm**
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known environment internal state environment





Arms respond in **Equilibrium**: **arm strategies** ∈ NE(Algorithm)

For t = 1, ..., T:

- 1) Every arm $i \in [K]$ privately observes true avg reward $\mu_{t,i}^* = \bigcirc \in \mathbb{R}$
- 2) Every arm $i \in [K]$ reports a gamed context $x_{t,i} = \mathbb{R}^d$ to the Algorithm
- 3) Algorithm plays arm $i_t = \{K\}$ and receives reward $r_t^*(i_t) \coloneqq \langle \theta^*, x_{t,i_t}^* \rangle + \eta_t$

known environment internal state environment





Arms respond in **Equilibrium**: **arm strategies** ∈ NE(Algorithm)

For t = 1, ..., T:

- 1) Every arm $i \in [K]$ privately observes true avg reward $\mu_{t,i}^* = \bigcirc \in \mathbb{R}$
- 2) Every arm $i \in [K]$ reports a gamed value $\mu_{t,i} = \bigoplus \in \mathbb{R}$ to the Algorithm
- 3) Algorithm plays arm $i_t = \{k\}$ $\in [K]$ and receives reward $r_t^*(i_t) \coloneqq \langle \theta^*, x_{t,i_t}^* \rangle + \eta_t$

known environment internal state ward environment





Arms respond in **Equilibrium**: **arm strategies** ∈ NE(Algorithm)

For t = 1, ..., T:

- 1) Every arm $i \in [K]$ privately observes true avg reward $\mu_{t,i}^* = \bigcirc \in \mathbb{R}$
- 2) Every arm $i \in [K]$ reports a gamed value $\mu_{t,i} = \bigoplus \in \mathbb{R}$ to the Algorithm
- 3) Algorithm plays arm $i_t = \{E\}$ $\in [K]$ and receives reward $r_t^*(i_t) \coloneqq \mu_{t,i_t}^* + \eta_t$

known environment





Arms respond in **Equilibrium**: **arm strategies** ∈ NE(Algorithm)

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known environment internal state server of the server of t



- Let's swap features $x \in \mathbb{R}^d$ for the implied avg reward $\mu := \langle \theta^*, x \rangle \in \mathbb{R}$
- We're happy when the arms "cooperate" and the *reports* $\mu_{t,i}$ match the **truth** $\mu_{t,i}^*$



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reports — truth

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The arms can misreport to us ... but not too often

Greedy Selection:

$$Play i_t = \arg \max_{i \in alive} \mu_{t,i}$$





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- 1) Under **GGTM**, being **truthful** is a \sqrt{T} -Nash Equilibrium.
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cost of mechanism design









Suppose the environment θ^* is unknown ...

Things get complicated ...

We observe: gamed context $x_{t,i}$ and reward $r_{t,i}^* \coloneqq \langle \theta^*, x_{t,i}^* \rangle + \eta_t$

We don't observe: true context $x_{t,i}^*$ and parameter θ^*

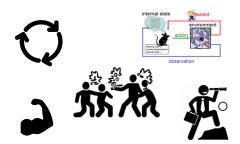
The arms can manipulate our estimate of θ^* ...

Estimating θ^* accurately becomes impossible?!

Another time ...

Short Recap

- Strategic Interactive Decision-Making
 - Reinforcement Learning + Mechanism Design
 - Objective: Strategic Robustness + Incentive Alignment



- Strategic Linear Contextual Bandits
 - Strategic agents manipulating contexts
 - Grim Trigger Mechanism from Iterated Social Dilemmas
 - Mechanism Design becomes approximate



• There are many more problems like this left to study ...

